

Paper Code: 77576.

CBS41.

1(b). $K = 1066.67 \text{ N/m}$
 $M = 0.1876 \text{ kg}$

(c) $\omega_n = 80.87 \text{ rad/s}$
 $C = 80870.27 \text{ Ns/m}$

(d). $K = 924.77 \text{ N/m}$
 $\text{New } \omega_n = 0.159 \text{ s}$

2(a). $M_y = M_1 + \frac{I_1}{r_2^2} + M_2 \left(\frac{r_1}{r_2} \right)^2$
 $K_y = K_1 + K_2 \left(\frac{r_1}{r_2} \right)^2$

$C_y = C$

$C = 1816.20 \text{ Ns/m}$

(b). $m\ddot{x} + \left[\frac{TL}{a(l-a)} \right] x = 0$

$\therefore \omega_n = \sqrt{\frac{TL}{ma(l-a)}} \text{ rad/s}$

3(a). $K = 353/0.02 = 2343750 \text{ N/m}$
 $\omega_n = 228.218 \text{ rad/s}$

$\frac{x}{F_0/k} = MF \cdot (\beta \omega)$

$\gamma = 0.856$ or $\gamma = 1.145$

$\omega = 195.35$ or 256.715

$N < 1565.45$ or > 2451.73
 rpm

(d) $f_n = 3.23 \text{ Hz}$; $\omega_n = 20.94 \text{ rad/s}$

$K_2 = 82.73 \text{ N/m}$

$\omega_n = 18.85 \text{ rad/s}$

$\omega = \sqrt{1 + \zeta^2} \omega_n$ ($\zeta = 0.435$)
 $\omega_n = 0.969$

Mechanical Vibrations

TE (Mech/Auto)

4(a) Error (max) when $\frac{dE}{d\gamma} = 0$

ie when $\gamma = \gamma^* = 2.202$

$\therefore \% \text{ Error} = \frac{-0.012}{\text{max}} \%$

(b). $\omega_{n1} = 0$

$\omega_{n2}; \omega_{n3} \neq 0$

5(a) Coulomb damping.

$\mu = 0.25$

$F = 5 \text{ N}$

$\omega_d = \omega_n = 14.14 \text{ rad/s}$

6(a). $\alpha_{11} = 0.0392/\text{s}$

$\alpha_{22} = 0.03/\text{s}$

$\alpha_{33} = 0.008/\text{s}$

$\alpha_{44} = 0.0392/\text{s}$

Dunkley's method.

$C = 161.77$

New $\omega_n = 15.80 \text{ rad/s}$

Mechanical Vibrations.

Subject Code: 37503; Paper Code: 27576.

Paper Solution:

Em VI / CBSGS / Mech-Auto / December 10, 2013.

(1). (b). $f_n = 12 \text{ Hz} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$

Also; $6 \text{ Hz} = \frac{1}{2\pi} \sqrt{\frac{k-800}{m}}$

$$\therefore \frac{6}{12} = \sqrt{\frac{k-800}{m}} \cdot \sqrt{\frac{m}{k}}$$

$$\therefore \frac{6}{12} = \sqrt{\frac{k-800}{k}}$$

$$\therefore 0.25k = k - 800$$

$$\therefore k = 1066.67 \text{ N/m}$$

$$\therefore m = 0.1876 \text{ kg}$$

(c). $m = 500 \text{ kg}$; $\delta_{st} = 1.5 \text{ mm}$; $\xi = 1$
 $c = ?$

$$\omega_n = \sqrt{g/\delta_{st}} = 80.87 \text{ rad/s}$$

$$\frac{c}{m} = 2\xi\omega_n \Rightarrow c = 2m\xi\omega_n = 80,870.27 \text{ Ns/m}$$

(d). $m = 5 \text{ kg}$; $t_{p1} = 0.45 \text{ sec}$

$t_{p2} = ?$

$$\frac{2.5}{2} 2k = 1949.55$$

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$$\frac{5}{5} k$$

$$\therefore 0.45 = 2\pi \sqrt{\frac{5}{k}}$$

$$\therefore k = 9749.77 \text{ N/m}$$

$$\frac{2.5}{2} 4k$$

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$$\frac{2.5}{2} 4k$$

$$\therefore t_{p2} = 2\pi \sqrt{\frac{2.5}{3899.10}} = 0.159 \text{ s}$$

2a. $C = ?$

$\xi = 1.25$

$r_1 = 0.1 \text{ m}$

$r_2 = 0.3 \text{ m}$

$I_p = 1.1 \text{ kgm}^2$

$m_1 = 10 \text{ kg}$

$m_2 = 25 \text{ kg}$

$k_1 = 1 \times 10^4 \text{ N/m}$

$k_2 = 1 \times 10^5 \text{ N/m}$

$x = r_2 \theta$

$\theta = \frac{x}{r_2}$



$y = r_1 \theta = r_1 \frac{x}{r_2}$

$KE = \frac{1}{2} m_1 \dot{x}^2 + \frac{1}{2} I_p \dot{\theta}^2 + \frac{1}{2} m_2 \dot{y}^2$

$= \frac{1}{2} m_1 \dot{x}^2 + \frac{1}{2} \left(\frac{I_p}{r_2^2} \right) \dot{x}^2 + \frac{1}{2} m_2 \left(\frac{r_1}{r_2} \right)^2 \dot{x}^2$

$= \frac{1}{2} \left[m_1 + \frac{I_p}{r_2^2} + m_2 \left(\frac{r_1}{r_2} \right)^2 \right] \dot{x}^2$

$PE = \frac{1}{2} k_1 x^2 + \frac{1}{2} k_2 \left(\frac{r_1}{r_2} \right)^2 x^2$

$= \frac{1}{2} \left[k_1 + k_2 \left(\frac{r_1}{r_2} \right)^2 \right] x^2$

$WD = - \int_{x_1}^{x_2} C \dot{x} dx$

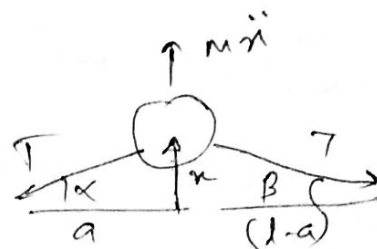
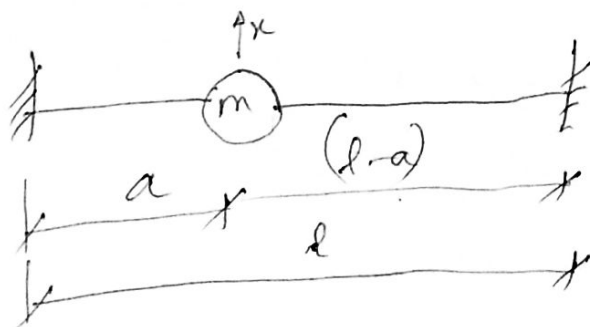
$\therefore C = \xi C \text{ Ns/m}$

$\frac{C_{eq}}{m_{eq}} = 2 \xi \omega_n$

$\therefore \frac{C}{\left[m_1 + \frac{I_p}{r_2^2} + m_2 \left(\frac{r_1}{r_2} \right)^2 \right]} = 2 \times 1.25 \times \sqrt{\frac{k_1 + k_2 \left(\frac{r_1}{r_2} \right)^2}{m_1 + \frac{I_p}{r_2^2} + m_2 \left(\frac{r_1}{r_2} \right)^2}}$

$\therefore C = 1816.20 \text{ Ns/m}$

b.



From Newton's 2nd law;

$m\ddot{x} + T(\sin\alpha + \sin\beta) = 0$

$\therefore m\ddot{x} + T \left[\frac{x}{a} + \frac{x}{(l-a)} \right] = 0$

$m\ddot{x} + T x \left[\frac{l-a+a}{a(l-a)} \right] = 0$

$\therefore m\ddot{x} + \left[\frac{TL}{a(l-a)} \right] x = 0$

$\therefore \omega_n = \sqrt{\frac{TL}{a(l-a)m}}$

3 (a). $m = 45 \text{ kg.}$
 $l = 1.6 \text{ m.}$
 $E = 2 \times 10^{11} \text{ N/m}^2.$
 $I = 1.6 \times 10^{-5} \text{ m}^4.$
 $F_0 = 125 \text{ N.}$
 $X \leq 0.2 \times 10^{-3} \text{ m.}$

$\omega = ? \text{ or } N = ?$

$K = \frac{3EI}{l^3} = 2343750 \text{ N/m.}$

$\omega_n = \sqrt{K/m} = 228.218 \text{ rad/s.}$

$\frac{X}{(F_0/K)} = \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}}$

$\therefore \frac{0.2 \times 10^{-3}}{(125/2343750)} = \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} = \frac{1}{|1-r^2|}$

$\therefore |1-r^2| = 0.2667$

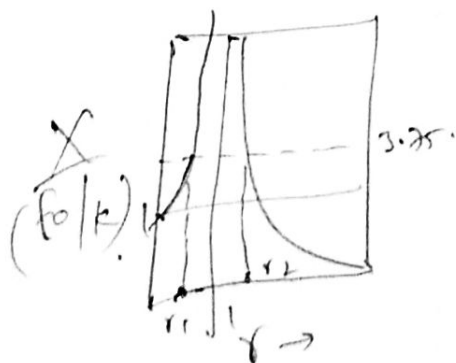
ie $1-r^2 = 0.2667$ or $r^2 - 1 = 0.2667$

ie $r = 0.856$ or $r = 1.125$

ie $\omega = 0.856 \omega_n$ or $\omega = 1.125 \omega_n$

ie $\omega = 195.35 \text{ rad/s}$ or $\omega = 246.745 \text{ rad/s}$

or $N = \frac{1865.45}{\text{rpm}}$ or $N = \underline{\underline{2451.73 \text{ rpm}}}$



$\therefore N \leq \frac{1865.45 \text{ rpm}}{1.1542}$

or $N \geq \underline{\underline{2451.73 \text{ rpm}}}$

3 d. Torsional pendulum.

$$f_n = \frac{200}{60} = 3.33 \text{ Hz.}$$

$$\therefore \omega_n = \underline{20.94 \text{ rad/s.}}$$

$$I = 0.2 \text{ kgm}^2.$$

$$\omega_n = \sqrt{\frac{k_t}{I}} \Rightarrow k_t = \underline{87.73 \text{ Nm/rad.}}$$

$$f_d = \frac{180}{60} = 3 \text{ Hz.}$$

$$\therefore \omega_d = 18.8495 \text{ rad/s.}$$

$$\text{Now; } \omega_d = \sqrt{1 - \xi^2} \omega_n.$$

$$\therefore 18.8495 = \sqrt{1 - \xi^2} \cdot (20.94)$$

$$\therefore \boxed{\xi = 0.435}.$$

Now;

$$\theta_0 = 2^\circ = \left(2 \times \frac{\pi}{180}\right)^\circ = \underline{0.0349^\circ}.$$

$$\dot{\theta}_0 = 0. \text{ rad/s.}$$

$$\delta = \ln\left(\frac{\theta_0}{\theta_1}\right) = \frac{2\pi\xi}{\sqrt{1-\xi^2}} = \ln\left(\frac{\theta_0}{\theta_1}\right).$$

$$\therefore \ln\left(\frac{2^\circ}{\theta_1}\right) = \frac{2\pi\xi}{\sqrt{1-\xi^2}} \Rightarrow 3.0354.$$

$$\therefore \boxed{\theta_1 = 0.096^\circ}.$$



4a. Max. % error of vibrometer = ?

$$\underline{4 \leq \lambda < \infty}, \quad \xi = 0.63.$$

% Error in vibrometer is given by:—
(E).

$$E = \frac{Y - Z}{Y} \times 100 \Rightarrow 1 - \frac{Z}{Y} \%$$

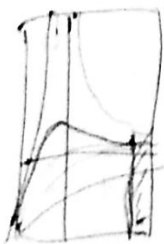
$$\text{Error factor} = \frac{r^2}{\sqrt{(1-r^2)^2 + (2\xi r)^2}}$$

Max. error occurs when $dE/dr = 0$.

$$\text{i.e.; } \lambda = r^* = \frac{1}{\sqrt{1-2\xi^2}} = \frac{1}{\sqrt{1-2(0.63)^2}}$$

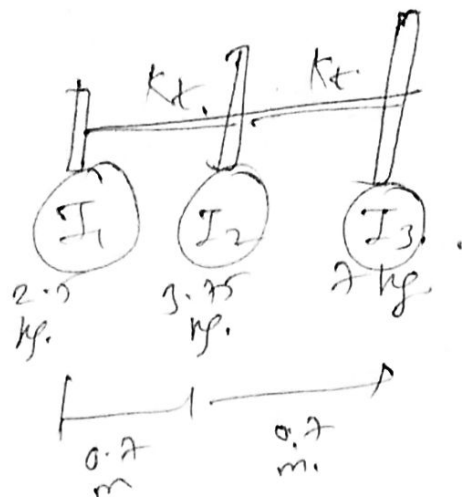
$$= \underline{\underline{2.202}}$$

$$\therefore \% \text{ Error} = 1 - \frac{2.202^2}{\sqrt{(1-2.202^2)^2 + (2 \times 0.63 \times 2.202)^2}}$$



$$= \underline{\underline{-0.02\%}}$$

46.

 $l = 10 \text{ cm.}$ $\omega_n^2 = ?$

$$K_t = \frac{I}{\Theta} = \frac{9 \times 10^8 \times \pi (0.1)^4}{0.7 \times 32}$$

$$= 12622.47 \frac{\text{Nm}}{\text{rad}}$$

$$k_1 = 0.2 \text{ m, } k_2 = 0.3 \text{ m,}$$

$$k_3 = 0.4 \text{ m.}$$

$$G = 9 \times 10^8 \text{ N/m}^2.$$

$$I_1 \ddot{\Theta}_1 + K_t (\Theta_1 - \Theta_2) = 0.$$

$$I_2 \ddot{\Theta}_2 - K_t (\Theta_1 - \Theta_2) + K_t (\Theta_2 - \Theta_3) = 0.$$

$$I_3 \ddot{\Theta}_3 - K_t (\Theta_2 - \Theta_3) = 0.$$

$$\therefore I_1 \ddot{\Theta}_1 + K_t \Theta_1 - K_t \Theta_2 = 0.$$

$$I_2 \ddot{\Theta}_2 - K_t \Theta_1 + 2K_t \Theta_2 - K_t \Theta_3 = 0$$

$$I_3 \ddot{\Theta}_3 - K_t \Theta_2 + K_t \Theta_3 = 0.$$

$$\begin{bmatrix} I_1 & 0 & 0 \\ 0 & I_2 & 0 \\ 0 & 0 & I_3 \end{bmatrix} \begin{bmatrix} \ddot{\Theta}_1 \\ \ddot{\Theta}_2 \\ \ddot{\Theta}_3 \end{bmatrix} + \begin{bmatrix} K_t & -K_t & 0 \\ -K_t & 2K_t & -K_t \\ 0 & -K_t & K_t \end{bmatrix} \begin{bmatrix} \Theta_1 \\ \Theta_2 \\ \Theta_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 2.5 & 0 & 0 \\ 0 & 3.75 & 0 \\ 0 & 0 & 7 \end{bmatrix} \begin{bmatrix} \ddot{\Theta}_1 \\ \ddot{\Theta}_2 \\ \ddot{\Theta}_3 \end{bmatrix} + \begin{bmatrix} 12622.47 & -12622.47 & 0 \\ -12622.47 & 25244.94 & -12622.47 \\ 0 & -12622.47 & 12622.47 \end{bmatrix} \begin{bmatrix} \Theta_1 \\ \Theta_2 \\ \Theta_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$[D] = \begin{bmatrix} 0.4 & 0 & 0 \\ 0 & 0.267 & 0 \\ 0 & 0 & 0.1429 \end{bmatrix} \begin{bmatrix} 12622.47 & -12622.47 & 0 \\ -12622.47 & 25244.94 & -12622.47 \\ 0 & -12622.47 & 12622.47 \end{bmatrix}$$

(M)⁻¹ (K)

$$\therefore [D] = \begin{bmatrix} 5049 & -5049 & 0 \\ -3320.2 & 6720.4 & -3320.2 \\ 0 & -1803.75 & 1803.75 \end{bmatrix}$$

$$|D - \lambda I| = 0$$

$$\therefore \begin{vmatrix} (5049 - \lambda) & (-5049) & 0 \\ (-3320.2) & (6720.4 - \lambda) & (-3320.2) \\ 0 & (-1803.75) & (1803.75 - \lambda) \end{vmatrix} = 0$$

$$\therefore \cancel{\lambda = 0} \rightarrow \text{unfeas.}$$

$$(5049 - \lambda) \{ (6720.4 - \lambda)(1803.75 - \lambda) - (-3320.2)(1803.75) \}$$

$$+ (5049) (-3320.2)(1803.75 - \lambda) = 0$$

$$\therefore \lambda_{1,2} = \underline{\underline{\text{unfeas.}}}$$

5(a).

$$M = 20 \text{ kg.}$$

$$k = 4000 \text{ N/m.}$$

Coulomb damping.

$$\frac{4F}{k} = \Delta = \underline{5 \text{ mm.}}$$

$$F = \mu N = \mu mg.$$

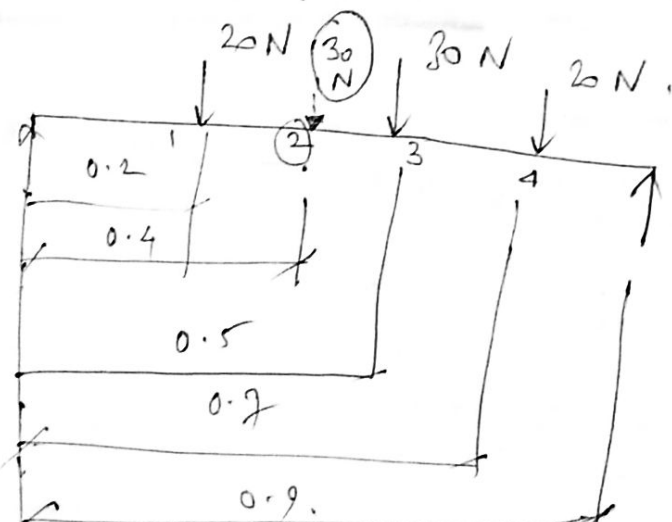
$$\therefore \frac{4 \times \mu (20)(9.81)}{4000} = \underline{5 \times 10^{-3}}.$$

$$\therefore \boxed{\mu = 0.025}.$$

$$\therefore \boxed{F = 5 \text{ N}}.$$

$$\omega_d = \omega_n = \sqrt{\frac{k}{m}} = \boxed{14.14 \text{ rad/s}}$$

6(a).



$$\alpha_{11} = \frac{(0.2)(0.7)(0.9^2 - 0.2^2 - 0.7^2)}{C} = 0.0392/c$$

$$\alpha_{33} = \frac{(0.5)(0.4)(0.9^2 - 0.5^2 - 0.4^2)}{C} = 0.08/c$$

$$\alpha_{44} = \frac{(0.7)(0.2)(0.9^2 - 0.7^2 - 0.2^2)}{C} = 0.0392/c.$$

$$\alpha_{22} = \frac{(0.4)(0.5)(0.9^2 - 0.4^2 - 0.5^2)}{C} = \alpha_{33} = 0.08/c.$$

Using Dunkley's method;

$$y_1 = \alpha_{11} W_1 = \frac{20 \times 0.0392}{c} = 0.784/c.$$

$$y_3 = \alpha_{33} W_3 = \frac{0.08}{c} \times 30 = 2.4/c.$$

$$y_4 = \alpha_{44} W_4 = \frac{0.0392}{c} \times 20 = 0.784/c.$$

$$\therefore \omega_n = \sqrt{\frac{g}{\sum_{i=1}^4 y_i}} \Rightarrow \omega = \sqrt{\frac{g}{\sum y_i}}.$$

$$\therefore \omega_c = \underline{161.79}.$$

$$\therefore y_1 = \underline{4.845 \times 10^{-3}} \text{ m.} = y_4.$$

$$\therefore y_3 = \underline{0.0148 \text{ m.}}$$

$$\text{Now; } y_2 = \alpha_{22} W_2 = \frac{0.08}{c} \times 30 = \frac{2.4}{c} = \underline{0.0148 \text{ m.}}$$

$$\therefore \text{New } \omega_n = \sqrt{\frac{g}{\sum_{i=1}^4 y_i}} = \boxed{15.80 \text{ rad/s.}}$$

Using Routhledge's method,

$$y_1 = \alpha_{11} w_1 = \frac{20 \times 0.079}{c} = 0.784/c,$$

$$y_3 = \alpha_{33} w_3 = \frac{0.91}{c} \times 30 = 2.4/c.$$

$$y_4 = \alpha_{44} w_4 = \frac{0.092}{c} \times 20 = 0.284/c.$$

$$\therefore \omega_n = \sqrt{\frac{g}{\sum_{i=1}^4 y_i}} \Rightarrow \omega_n = \sqrt{\frac{g}{\sum y_i}}.$$

$$\therefore c = 161.79.$$

$$\therefore y_1 = \frac{4.215 \times 10^{-8}}{m} = y_4.$$

$$\therefore y_3 = 0.0148 \text{ m}.$$

$$\text{Now, } y_2 = \alpha_{22} w_2 = \frac{0.09}{c} \times 30 = \frac{2.4}{c} = 0.0148 \text{ m}.$$

$$\therefore \text{New } \omega_n = \sqrt{\frac{g}{\sum y_i}} = \boxed{15.80 \text{ rad/s}}.$$