

steady state error for step input

$$e_{ss1} = \frac{A_1}{1+K_P} = 0$$

for ramp input $e_{ss2} = \frac{A_2}{1 < K_V} = 0$

for parabolic input

$$e_{ss3} = \frac{1}{0.5} = 2$$

total steady state error = 2

Q2. (c)
$$\frac{Y(s)}{U(s)} = \frac{2s^3 + s^2 + s + 2}{s^3 + 4s^2 + 5s + 2}$$

$$\ddot{y} + 4\dot{y} + 5y + 2y = 2\ddot{u} + \dot{u} + u + 2u$$

$\Rightarrow 0$

$$\beta_0 = b_0 - a_1\beta_1 - a_2\beta_2 = -7$$

$$\beta_2 = b_2 - a_1\beta_1 - a_2\beta_0 = 19$$

$$\beta_3 = b_3 - a_1\beta_2 - a_2\beta_1 - a_3\beta_0 = -43$$

output eqn.

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -5 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} -7 \\ 19 \\ -43 \end{bmatrix} U$$

$$y = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + 2U$$

Q 5 (b) max. deflection = $\Delta_m = \frac{3P}{16Et^3} R^4 (1-\nu^2)$, but $\Delta_m = t/3$

$$t/3 = \frac{3P}{16Et^3} R^4 (1-\nu^2) \Rightarrow t^4 = \frac{9P}{16E} R^4 (1-\nu^2)$$

$$t = 0.408 \times 10^{-3} \text{ m} = 0.408 \text{ mm}$$

$$f_n = \frac{2.5t}{\pi R^2} \left[\frac{E}{3P} (1-\nu^2) \right]^{1/2}$$

$$= \frac{2.5 \times 0.408 \times 10^{-3}}{\pi \times 6.25} \left[\frac{200 \times 10^9}{3 \times 7800 (1-0.28^2)} \right]^{1/2}$$

$$= 35.66 \text{ kHz}$$