

(3 Hours)

[Total Marks: 100]

Note: (i) All questions are compulsory.

(ii) Figures to the right indicate marks for respective parts.

Q.1	Choose correct alternative in each of the following:				(20)
i.	Integrating factor of $(2x \log x - xy)dy + 2ydx = 0$ is				
(a)	$\frac{1}{x}$	(b)	$\frac{1}{x^2}$		
(c)	x	(d)	None of the above.		
Ans	i.(a)				
ii.	The equation of the orthogonal trajectories to the family of parabolas $y^2 = kx$ is				
(a)	$\frac{y^2}{2} + x^2 = c$	(b)	$y = ce^{2x}$		
(c)	$y^2 + x^2 = c$	(d)	None of these		
Ans	ii(a)				
iii.	The degree of the O.D.E. $y' + x = (y - xy')^{-2}$ is				
(a)	1	(b)	2		
(c)	3	(d)	None of these		
Ans	iii(b)				
iv.	Which of the following is a homogenous first order differential equation?				
(a)	$\frac{dy}{dx} = \frac{2x + 3y}{2x - 3y}$	(b)	$\frac{dy}{dx} = \frac{2x + 3y + 1}{2x - 3y}$		
(c)	$\frac{dy}{dx} = \frac{2x + 3y}{2x - 3y + 1}$	(d)	$\frac{dy}{dx} = \frac{2x + 3y + 1}{2x - 3y - 1}$		
Ans	iv.(a)				
v.	General solution of $y'' + 16y = 0$ is $y =$				
(a)	$c_1 e^{4x} + c_2 e^{-4x}$	(b)	$(c_1 + c_2 x)e^{4x}$		
(c)	$c_1 \sin 4x + c_2 \cos 4x$	(d)	$c_1 x^4 + c_2 x^{-4}$		
Ans	v. (c)				
vi.	General solution for differential equation $y'' + y' = 0$ is				
(a)	$y = c_1 e^x + c_2 e^{-x}$	(b)	$y = c_1 + c_2 e^{-x}$		
(c)	$y = c_1 \cos x + c_2 \sin x$	(d)	$y = c_1 + c_2 e^x$		
Ans	vi. (b)				
vii.	Wronskian determinant $W(y_1, y_2)$ with usual symbols is equal to				
(a)	$y_1 y_2' - y_2 y_1'$	(b)	$y_1 y_2' + y_2 y_1'$		
(c)	$y_1 y_1' - y_2 y_2'$	(d)	$y_1 y_1' + y_2 y_2'$		
Ans	vii. (a)				
viii.	One of the solutions of the homogeneous linear system of differential equations $\begin{cases} \frac{dx}{dt} = 3x \\ \frac{dy}{dt} = 4y \end{cases}$ is				
(a)	$\begin{cases} x = 3e^{3t} \\ y = e^{4t} \end{cases}$	(b)	$\begin{cases} x = 3e^t \\ y = 4e^t \end{cases}$		

	(c)	$\begin{cases} x = 3e^{2t} \\ y = 5e^{3t} \end{cases}$	(d)	None of these		
	Ans	viii.(a)				
ix.	Amongst the following, the pair of linearly independent solutions is					
	(a)	$\begin{cases} x = e^t \\ y = e^t \end{cases}$ and $\begin{cases} x = e^{-t} \\ y = 2e^{-t} \end{cases}$	(b)	$\begin{cases} x = e^t \\ y = e^t \end{cases}$ and $\begin{cases} x = 3e^t \\ y = 3e^t \end{cases}$		
	(c)	$\begin{cases} x = e^t \\ y = -e^{3t} \end{cases}$ and $\begin{cases} x = -e^t \\ y = e^{3t} \end{cases}$	(d)	None of these		
	Ans	ix.(a)				
x.	The Wronskian of two solutions $\begin{cases} x = e^{2t} \\ y = 2e^{2t} \end{cases}$ and $\begin{cases} x = e^{3t} \\ y = 2e^{3t} \end{cases}$, of a homogeneous linear system of differential equations, is equal to					
	(a)	$4e^{5t}$	(b)	$2e^{2t}$		
	(c)	0	(d)	None of these		
	Ans	x. (c)				
Q.2	a)	Attempt any ONE question from the following:				(08)
	i.	Show that the general solution of the linear first order O.D.E. $\frac{dy}{dx} + Py = Q$, P and Q are integrable functions of x , is $y = e^{-\int P dx} \left(\int Q e^{\int P dx} dx + c \right)$, c being an arbitrary constant. Hence solve the O.D.E. $\frac{dy}{dx} + \frac{y}{1-x} = x^2 - x$.				
		Consider $\frac{d}{dx}(ye^{\int P dx})$. We have by the product rule of differentiation $\frac{d}{dx}(ye^{\int P dx}) = \frac{dy}{dx} e^{\int P dx} + y \frac{d}{dx}(e^{\int P dx})$ $= \frac{dy}{dx} e^{\int P dx} + ye^{\int P dx} \frac{d}{dx}(\int P(x) dx) \dots \text{by Chain Rule}$ $= \frac{dy}{dx} e^{\int P dx} + ye^{\int P dx} P(x)$ $= e^{\int P dx} \left(\frac{dy}{dx} + P(x)y \right)$ $= Q(x)e^{\int P dx} \dots \dots (\because \frac{dy}{dx} + Py = Q)$ <p>Hence $ye^{\int P dx} = \int Q(x)e^{\int P dx} dx + c$, upon integration. $\therefore y = e^{-\int P dx} \left(\int Qe^{\int P dx} dx + c \right)$ is the required solution.</p> <p>The given O.D.E. is linear with $P = \frac{1}{1-x}$ & $Q = x^2 - x$ \therefore its solution is given by $y = e^{-\int P dx} \left(\int Qe^{\int P dx} dx + c \right)$$= e^{-\log(1-x)} \left(\int (x^2 - x)e^{\log(1-x)} dx + c \right)$$= \frac{1}{1-x} \left(\int (x^2 - x)(1-x) dx + c \right)$$= \frac{1}{1-x} \left(\int (-x^3 + 2x^2 - x) dx + c \right)$$= \frac{1}{1-x} \left(-\frac{x^4}{4} + \frac{2x^3}{3} - \frac{x^2}{2} + c \right), \text{ is the required solution.}$</p>				1 1 1 1 1 1 1 1
	ii.	Verify that the given differential equation is not exact. Further, find an				

3

		I.F. of the differential equation and solve: $(x^3 - 2y^3 - 3xy)dx + 3x(y^2 + x)dy = 0$.	
		Sol: Comparing the given differential equation with $M dx + N dy = 0$, $M = x^3 - 2y^3 - 3xy$ and $N = 3xy^2 + 3x^2$ $\therefore \frac{\partial M}{\partial y} = -6y^2 - 3x$ and $\frac{\partial N}{\partial x} = 3y^2 + 6x$ $\therefore \frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, \therefore the given differential equation is not exact.	2
		Now, $\frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) = \frac{1}{3xy^2 + 3x^2} (-6y^2 - 3x - 3y^2 - 6x) = \frac{-9(y^2 + x)}{3x(y^2 + x)}$ $= -\frac{3}{x}$, which is a function of x alone. $\therefore I.F = e^{\int \frac{-3}{x} dx} = e^{-3 \log x} = \frac{1}{x^3}$	3
		Multiplying the given differential equation by I.F = $\frac{1}{x^3}$ we get the exact differential equation $\frac{(x^3 - 2y^3 - 3xy)}{x^3} dx + \frac{3x(y^2 + x)}{x^3} dy = 0$ Its solution is, $\int \frac{(x^3 - 2y^3 - 3xy)}{x^3} dx = c$ i.e. $\int dx - 2y^3 \int \frac{1}{x^3} dx - 3y \int \frac{1}{x^2} dx = c$ or that $x + \frac{y^3}{x^2} + \frac{3y}{x} = c$	3
	b)	Attempt any TWO questions from the following:	(12)
	i.	By Substituting $x + y = v$, solve the differential equation: $(x + y)^2 \frac{dy}{dx} = 1$	
		Sol:- $x + y = v$ $1 + \frac{dy}{dx} = \frac{dv}{dx}$ $\therefore \frac{dy}{dx} = \frac{dv}{dx} - 1$ $\therefore v^2 \left(\frac{dv}{dx} - 1 \right) = 1$ $\therefore \frac{dv}{dx} = \frac{1}{v^2} + 1$ $\therefore \frac{dv}{v^2 + 1} dx = dv$ $\therefore \left(1 - \frac{1}{v^2 + 1} \right) dv = dx$ $\therefore \int \left(1 - \frac{1}{v^2 + 1} \right) dv = \int dx$ $\therefore v - \tan^{-1} v = x + c$ $\therefore x + y - \tan^{-1}(x + y) = x + c$ $\therefore y = \tan^{-1}(x + y) + c$	1 1 1 1 1 1 1
	ii.	Solve the following non-homogenous differential equation: $\frac{dy}{dx} = \frac{x + 2y - 1}{x + 2y + 1}$	
		Sol:	

9

			$\frac{dy}{dx} = \frac{x+2y-1}{x+2y+1} \dots (1)$	1
			Put $x+2y = v$ $\therefore \frac{dy}{dx} = \frac{1}{2} \frac{dv}{dx} - \frac{1}{2}$	1
			Substituting in (1), we get, $\frac{dv}{dx} = \frac{3v-1}{v+1}$	1
			$\therefore \frac{1}{3v-1} dv = dx$	1
			$\therefore \frac{1}{3} \left(1 + \frac{4}{3v-1} \right) dv = dx$	1
			Integrating, we get, $\int \left(1 + \frac{4}{3v-1} \right) dv = 3 \int dx + c$ $\therefore v + \frac{4}{3} \log(3v-1) = 3x + c$	1
			Substituting back $v = x+2y$, we get, $3x - 3y - 2 \log(3x+6y-1) = k$	1
		iii.	Solve the differential equation: $\frac{dy}{dx} + \frac{y}{x} = x^2 y^6$	
			Sol: - The given differential equation is a Bernoulli's equation Now, putting $v = y^{-5}$ the equation transforms to $\frac{dv}{dx} - 5 \frac{v}{x} = -5x^2$, which is linear and has solution $v e^{\int -\frac{5}{x} dx} = - \int 5x^2 e^{\int -\frac{5}{x} dx} dx + c$	1
			i.e. $\frac{1}{y^5} \frac{1}{x^5} = - \int 5x^2 \left(\frac{1}{x^5} \right) dx + c$ i.e. $\frac{1}{x^5 y^5} = \frac{5}{2x^2} + c$	2
		iv.	An RL circuit has an emf of 15V, a resistance of 90Ω and inductance of 3H, and no initial current. Find the current in the circuit at any time t.	
			Sol: $V = 15$, $R = 90$, $L = 3$ We have $\frac{di}{dt} + \frac{R}{L} i = \frac{V(t)}{L}$ $\therefore \frac{di}{dt} + \frac{90}{3} i = \frac{15}{3}$	1
			$\therefore \frac{di}{dt} + 30 i = 5$	1
			$\therefore \frac{di}{dt} = 5 - 30 i$	1
			$\therefore \frac{di}{dt} = 5(1 - 6i)$	1
			$\therefore \frac{di}{1-6i} = 5 dt$	1
			$\therefore \int \frac{di}{1-6i} = 5 \int dt$ $\therefore \frac{\log(1-6i)}{-6} = 5t + c$ At $t = 0, i = 0$ given, $\therefore \frac{\log 1}{-6} = 0 + c \text{ from (1)}$	1

		$\therefore c = 0$ $\therefore (1) \text{ becomes}$ $\therefore \frac{\log(1 - 6i)}{-6} = 5t$ $\therefore \log(1 - 6i) = -30t$ $\therefore (1 - 6i) = e^{-30t}$ $\therefore 6i = 1 - e^{-30t}$ $\therefore i = \frac{1 - e^{-30t}}{6}$	1
			1
Q.3	a)	Attempt any ONE question from the following:	(08)
	i.	Let $y_1(x)$ be a non-zero solution to the differential equation $y'' + P(x)y' + Q(x)y = 0$ on $[a, b]$ then show that another linearly independent solution $y_2(x) = y_1(x) \int \frac{e^{\int -p(x)dx}}{y_1^2(x)} dx$	
	Ans	<p>Let $y_1(x)$ and $y_2(x)$ are two independent solution of the differential equation $y'' + P(x)y' + Q(x)y = 0$</p> <p>$\therefore \exists$ non constant function $V(x)$ such that,</p> $y_2(x) = V(x)y_1(x) \quad (1)$ $\therefore y_2' = Vy_1' + y_1V'$ $y_2'' = Vy_1'' + 2V'y_1' + V''y_1$ <p>Substituting these values in $y_2'' + P(x)y_2' + Q(x)y_2 = 0$</p> $\therefore Vy_1'' + 2V'y_1' + V''y_1 + P(Vy_1' + y_1V') + QV(x)y_1(x) = 0$ $\therefore V(y_1'' + Py_1' + Qy_1) + V''y_1 + V'(2y_1' + Py_1) = 0 \quad (2)$ <p>As y_1 is a solution to $y'' + P(x)y' + Q(x)y = 0$</p> $\therefore y_1'' + P(x)y_1' + Q(x)y_1 = 0$ <p>hence equation (2) becomes</p> $V''y_1 + V'(2y_1' + Py_1) = 0$ $\therefore V''y_1 = -V'(2y_1' + Py_1)$ $\therefore \frac{V''}{V'} = -\frac{(2y_1' + Py_1)}{y_1}$ $\therefore \frac{V''}{V'} = -\frac{2y_1'}{y_1} - P$ <p>Integrating both sides we get,</p> $\log V' = -2 \log y_1 - \int P dx$ $\therefore \log V' + 2 \log y_1 = -\int P dx$ $\therefore \log V' + \log y_1^2 = -\int P dx$ $\therefore \log(V'y_1^2) = -\int P dx$ $\therefore V'y_1^2 = e^{-\int P dx}$ $\therefore V' = \frac{1}{y_1^2} e^{-\int P dx}$ $\therefore V = \int \frac{1}{y_1^2} e^{-\int P dx} dx$ <p>$\therefore (2) \text{ becomes}$</p> $y_2(x) = y_1(x) \int \frac{1}{y_1^2} e^{-\int P dx} dx$ <p>Now we shall show that, $y_1(x)$ and $y_2(x)$ are linearly independent.</p> $\therefore W(y_1, y_2) = y_1y_2' - y_2y_1'$	1 1 1 1 1 1 1

		$= y_1(Vy_1 + V'y_1) - Vy_1y_1'$ $= V'y_1^2 \text{ as } V' = y_1(x) \int \frac{1}{y_1^2} e^{-\int P dx} dx \text{ is never zero,}$ $\text{and } y_1^2 \neq 0$ $\therefore W(y_1, y_2) \text{ is never zero.}$ $\therefore y_1 \text{ and } y_2 \text{ are linearly independent}$	1
	ii.	Describe the method of variation of parameters to solve a non-homogenous differential equation of the second order.	
	Ans	<p>Let $y_1(x)$ and $y_2(x)$ are solutions of the differential equation $y'' + py' + qy = 0$</p> <p>\therefore complementary function is</p> $y_c = c_1y_1 + c_2y_2$ <p>Let particular integral for $y'' + py' + qy = R(x)$ be</p> $y_p = uy_1 + vy_2 \quad \dots (1)$ $\therefore y_p' = u'y_1 + uy_1' + v'y_2 + vy_2' \quad \dots (2)$ <p>Let u, v satisfy the equation</p> $u'y_1 + v'y_2 = 0 \quad \dots (3)$ <p>\therefore equation (2) becomes</p> $\therefore y_p' = uy_1' + vy_2'$ $\therefore y_p'' = u'y_1' + uy_1'' + v'y_2' + vy_2''$ <p>Substituting these values in $y_p'' + py_p' + qy_p = R(x)$,</p> $\therefore u'y_1' + uy_1'' + v'y_2' + vy_2'' + p(uy_1' + vy_2') + q(uy_1 + vy_2) = R(x)$ $\therefore u(y_1'' + py_1' + qy_1) + v(y_2'' + py_2' + qy_2) + (u'y_1' + v'y_2') = R(x)$ <p>$[\because y_1 \text{ and } y_2 \text{ are solutions for } y'' + py' + qy = 0]$</p> $\therefore u(0) + v(0) + (u'y_1' + v'y_2') = R(x)$ $\therefore (u'y_1' + v'y_2') - R = 0 \quad \dots (4)$ <p>Using Cramer's Rule for equations (3) and (4) we get,</p> $\frac{u'}{\begin{vmatrix} y_2 & 0 \\ y_2' & -R \end{vmatrix}} = \frac{-v'}{\begin{vmatrix} y_1 & 0 \\ y_1' & -R \end{vmatrix}} = \frac{1}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$ $\frac{u'}{\begin{vmatrix} y_2 & 0 \\ y_2' & -R \end{vmatrix}} = \frac{-v'}{\begin{vmatrix} y_1 & 0 \\ y_1' & -R \end{vmatrix}} = \frac{1}{W}$ $\therefore \frac{u'}{-y_2R} = -\frac{v'}{-y_1R} = \frac{1}{W}$ $\therefore u' = -\frac{y_2R}{W} \text{ and } v' = \frac{y_1R}{W}$ $\therefore u = -\int \frac{y_2R}{W} dx \text{ and } v = \int \frac{y_1R}{W} dx$	1 1 1 1 1 1 1 1 1 1

b)		Attempt any TWO questions from the following:	(12)
i.		Find the general solution for the differential equation $y'' - 7y' + 12y = 0$	
Ans		Associated auxiliary equation $x^2 - 7x + 12 = 0 \therefore x = 3$ and $x = 4$ are the two roots. $\therefore y_1(x) = e^{3x}$ is one solution. $y_2(x) = e^{4x}$ are two linearly independent solution. $\therefore y(x) = c_1 e^{3x} + c_2 e^{4x}$ is general solution.	2 2 2
ii.		Solve the non-homogenous differential equation $\frac{d^2y}{dx^2} + 4\frac{dy}{dx} + 5y = x + 12$.	
Ans		Auxiliary equation is $m^2 + 4m + 5 = 0$ $\therefore (m + 1)(m + 4) = 0$ $\therefore m = -1, -4$ $\therefore y_c = c_1 e^{-x} + c_2 e^{-4x}$ Let $y_p = Ax + B$ $\therefore y_p' = A$ $y_p'' = 0$ $\therefore y_p'' + 4y_p' + 5y_p = x + 12$ $\therefore 0 + 4A + 5(Ax + B) = x + 12$ $\therefore A = \frac{1}{5}, \quad 4A + 5B = 12$ $\therefore B = \frac{56}{25}$ $\therefore y_p = \frac{1}{5}x + \frac{56}{25}$ \therefore general solution is $y = y_c + y_p$ $\therefore y = c_1 e^{-x} + c_2 e^{-4x} + \frac{1}{5}x + \frac{56}{25}$	1 1 1 1 1 1 1
iii.		Solve the differential equation $\frac{d^2y}{dx^2} + 3\frac{dy}{dx} - 10y = 6e^{4x}$	
Ans		Associated auxiliary equation of homogeneous system is $x^2 + 3x - 10 = 0 \therefore x = -5$ & $x = 2 \therefore y_1(x) = e^{-5x}$ & $y_2(x) = e^{2x}$ Are linearly independent solutions of associated homogeneous system Take $y_p(x) = Ae^{4x}$ then $A = \frac{1}{3} \therefore y(x) = c_1 e^{-5x} + c_2 e^{2x} + \frac{1}{3}e^{4x}$ is the general solution of given D.E.	3 1 2
iv.		Using the method of variation of parameters solve $\frac{d^2y}{dx^2} + 4y = \sin x$	
Ans		Auxiliary equation for the differential equation is $m^2 + 4 = 0$ $\therefore m = \pm 2i$ $\therefore y_c = c_1 \cos 2x + c_2 \sin 2x$ \therefore two independent solution for $\frac{d^2y}{dx^2} + 4y = 0$ are	1

		$y_1(x) = \cos 2x \text{ and } y_2(x) = \sin 2x$ $\therefore y_1'(x) = -2 \cos 2x \text{ and } y_2'(x) = 2 \sin 2x$ $\therefore W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$ $= \begin{vmatrix} \cos 2x & \sin 2x \\ -2 \sin 2x & 2 \cos 2x \end{vmatrix}$ $= 2$ <p>Here $R = e^x \sin x$</p> $\therefore u = - \int \frac{y_2 R}{W} dx$ $= - \int \frac{\sin 2x \sin x}{2} dx$ $= -\frac{1}{4} \int 2 \sin 2x \sin x dx$ $= \frac{1}{4} \int (\cos x - \cos 3x) dx$ $= \frac{1}{4} (-\sin x + \frac{1}{3} \sin 3x)$ <p>and</p> $v = \int \frac{y_1 R}{W} dx$ $= \int \frac{\cos 2x \sin x}{2} dx$ $= \frac{1}{4} \int 2 \cos 2x \sin x dx$ $= \frac{1}{4} \int (\sin 3x - \sin x) dx$ $= \frac{1}{4} (-\frac{1}{3} \cos 3x + \sin x)$ <p>\therefore particular integral is $y_p = uy_1 + vy_2$</p> $\therefore y_p = \frac{1}{4} \sin 2x (-\frac{1}{3} \cos 3x + \sin x)$ <p>\therefore particular solution is $y = y_c + y_p$</p> $\therefore y = \frac{1}{4} \cos 2x \left(-\sin x + \frac{1}{3} \sin 3x \right) + \frac{1}{4} \sin 2x \left(-\frac{1}{3} \cos 3x + \sin x \right)$	1 1 1 1 1 1
Q.4	a)	Attempt any ONE question from the following:	(08)
	i.	<p>Prove that the two solutions $\begin{cases} x = x_1(t) \\ y = y_1(t) \end{cases}$ and $\begin{cases} x = x_2(t) \\ y = y_2(t) \end{cases}$ of the homogeneous linear system</p> $\begin{cases} \frac{dx}{dt} = a_1(t)x + b_1(t)y \\ \frac{dy}{dt} = a_2(t)x + b_2(t)y \end{cases}$ <p>are linearly dependent on $[a, b]$ iff their Wronskian is identically zero on $[a, b]$.</p>	
		<p>Solution:</p> <p>If the solutions are linearly dependent, then it means there exists a real number k, such that $x_1(t) = kx_2(t)$ and $y_1(t) = ky_2(t)$. Then,</p>	

9

		$W[T] = \begin{vmatrix} x_1(t) & x_2(t) \\ y_1(t) & y_2(t) \end{vmatrix} = \begin{vmatrix} x_1(t) & x_2(t) \\ kx_1(t) & kx_2(t) \end{vmatrix} = kx_1(t)x_2(t) - kx_2(t)x_1(t) = 0$	2
		<p>It should be clear that $W[T] = 0$, if $kx_1(t) = x_2(t)$ and $ky_1(t) = y_2(t)$</p> <p>Now suppose, the Wronskian is identically zero on $[a, b]$. We will show that the solutions are dependent. That is, we will show that there exist real numbers c_1 and c_2, not both zero, such that</p> $c_1x_1(t) + c_2x_2(t) = 0$ $c_1y_1(t) + c_2y_2(t) = 0$ <p>Let $t_0 \in [a, b]$. Then $W(t_0) = 0$. Hence, the following system of linear algebraic equations has a solution c_1, c_2, in which these numbers are not both zero.</p> $c_1x_1(t_0) + c_2x_2(t_0) = 0$ $c_1y_1(t_0) + c_2y_2(t_0) = 0$ $x = c_1x_1(t_0) + c_2x_2(t_0)$ $y = c_1y_1(t_0) + c_2y_2(t_0) \dots (*)$ <p>Thus, the solution of the system, given by $y = c_1y_1(t_0) + c_2y_2(t_0) \dots (*)$ equals the trivial solution at t_0.</p> <p>Now from the uniqueness part of the Existence and Uniqueness theorem, it follows that $(*)$ must equal the trivial solution throughout the interval $[a, b]$.</p>	3
	ii.	<p>State the theorem for existence and uniqueness of first order homogeneous linear system of O.D.E. in two variables. Let $\begin{cases} x = x_1(t) \\ y = y_1(t) \end{cases}$ and $\begin{cases} x = x_2(t) \\ y = y_2(t) \end{cases}$ be two solutions of the homogeneous system $\begin{cases} \frac{dx}{dt} = a_1(t)x + b_1(t)y \\ \frac{dy}{dt} = a_2(t)x + b_2(t)y \end{cases}$ where a_1, a_2, b_1, b_2 are continuous functions on $[a, b]$. Show that the linear independence and continuity of the solutions on $[a, b]$ implies $\begin{cases} x = c_1x_1(t) + c_2x_2(t) \\ y = c_1y_1(t) + c_2y_2(t) \end{cases}$ to be the general solution of the homogeneous system on $[a, b]$.</p>	
		<p>Solution: The linear system of homogeneous first order ordinary differential</p>	

equations given as
$$\begin{cases} \frac{dx}{dt} = a_1(t)x(t) + b_1(t)y(t) \\ \frac{dy}{dt} = a_2(t)x(t) + b_2(t)y(t) \end{cases} \quad \text{-----} \quad *$$

2

where $a_1(t)$, $a_2(t)$, $b_1(t)$, $b_2(t)$ are continuous functions defined on interval $[a, b]$ has a unique solution $((x(t), y(t)))$ satisfying initial conditions $x(t_0) = x_0$ & $y(t_0) = y_0$ for some $t_0 \in [a, b]$.

Let $(x_1(t), y_1(t))$ & $(x_2(t), y_2(t))$ where $x_1(t), y_1(t), x_2(t), y_2(t)$ are continuously differentiable on $[a, b]$, be two linearly independent solutions of $*$, i.e., $W(t) \neq 0, \forall t \in [a, b]$.

Then,

$$\begin{cases} x_1'(t) = a_1(t)x_1(t) + b_1(t)y_1(t) \\ y_1'(t) = a_2(t)x_1(t) + b_2(t)y_1(t) \end{cases} \text{ and}$$

$$\begin{cases} x_2'(t) = a_1(t)x_2(t) + b_1(t)y_2(t) \\ y_2'(t) = a_2(t)x_2(t) + b_2(t)y_2(t) \end{cases}$$

2

$$\begin{aligned} \text{Now } (c_1x_1)'(t) &= c_1x_1'(t), (c_1y_1)'(t) = c_1y_1'(t), \\ (c_2x_2)'(t) &= c_2x_2'(t), (c_2y_2)'(t) = c_2y_2'(t) \end{aligned}$$

$$\begin{aligned} a_1(t)(c_1x_1)(t) + b_1(t)(c_1y_1)(t) &= c_1(a_1(t)x_1(t) + b_1(t)y_1(t)) \\ a_2(t)(c_1x_1)(t) + b_2(t)(c_1y_1)(t) &= c_1(a_2(t)x_1(t) + b_2(t)y_1(t)) \end{aligned}$$

Similarly for c_2x_2 & c_2y_2

Thus verifying that $(c_1x_1 + c_2x_2, c_1y_1 + c_2y_2)$ satisfies $*$

Now let $((x(t), y(t)))$ satisfying initial conditions $x(t_0) = x_0$ & $y(t_0) = y_0$ for some $t_0 \in [a, b]$ be a particular solution to $*$ then consider the equations

$$\begin{aligned} c_1x_1(t_0) + c_2x_2(t_0) &= x_0 \\ c_1y_1(t_0) + c_2y_2(t_0) &= y_0 \\ \therefore \begin{bmatrix} x_1(t_0) & x_2(t_0) \\ y_1(t_0) & y_2(t_0) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} &= \begin{bmatrix} x_0 \\ y_0 \end{bmatrix} \end{aligned}$$

2

The above matrix equation has a unique solution provided

$$\det \begin{bmatrix} x_1(t_0) & x_2(t_0) \\ y_1(t_0) & y_2(t_0) \end{bmatrix} \neq 0$$

But as $W(t) \neq 0, \forall t \in [a, b]$ hence $W(t_0) \neq 0$

\therefore For above values of c_1, c_2 , $(c_1x_1 + c_2x_2, c_1y_1 + c_2y_2)$ Satisfies $*$ but

11

		<p>due to uniqueness of solution satisfying initial conditions hence</p> $c_1x_1 + c_2x_2 = x \text{ \& } c_1y_1 + c_2y_2 = y.$ <p>Thus $(c_1x_1 + c_2x_2, c_1y_1 + c_2y_2)$ is general solution to * for arbitrary constants c_1 & c_2.</p>	2
	b)	Attempt any TWO questions from the following:	(12)
	i.	<p>Show that both $\begin{cases} x = e^{3t} \\ y = e^{3t} \end{cases}$ and $\begin{cases} x = e^{2t} \\ y = 2e^{2t} \end{cases}$ are solutions of the system</p> $\begin{cases} \frac{dx}{dt} = 4x - y \\ \frac{dy}{dt} = 2x + y \end{cases}$ <p>Hence or otherwise, write general solution of the system.</p> <p>Solution:</p> <p>Consider $\begin{cases} x = e^{3t} \\ y = e^{3t} \end{cases}$. Therefore,</p> $\begin{aligned} \frac{dx}{dt} &= 3e^{3t} & \frac{dy}{dt} &= 3e^{3t} \\ &= 4e^{3t} - e^{3t} & &= 2e^{3t} + e^{3t} \\ &= 4x - y & &= 2x + y \end{aligned}$ <p>Thus, $\begin{cases} x = e^{3t} \\ y = e^{3t} \end{cases}$ satisfies the given system.</p> <p>Similarly, consider $\begin{cases} x = e^{2t} \\ y = 2e^{2t} \end{cases}$. Therefore,</p> $\begin{aligned} \frac{dx}{dt} &= 2e^{2t} & \frac{dy}{dt} &= 4e^{2t} \\ &= 4e^{2t} - 2e^{2t} & &= 2e^{2t} + 2e^{2t} \\ &= 4x - y & &= 2x + y \end{aligned}$ <p>Thus, $\begin{cases} x = e^{2t} \\ y = 2e^{2t} \end{cases}$ too satisfies the given system.</p> <p>Consider the Wronskian of the two solutions:</p> $\begin{aligned} W &= \begin{vmatrix} e^{3t} & e^{2t} \\ e^{3t} & 2e^{2t} \end{vmatrix} \\ &= 2e^{5t} - e^{5t} \\ &= e^{5t} \end{aligned}$ <p>Since, exponential function never vanishes, $W \neq 0$. Therefore, the two solutions $\begin{cases} x = e^{3t} \\ y = e^{3t} \end{cases}$ and $\begin{cases} x = e^{2t} \\ y = 2e^{2t} \end{cases}$ are linearly independent.</p> <p>Thus, the general solution of the system is</p>	2

1.2

		$\begin{cases} x = c_1 e^{3t} + c_2 e^{2t} \\ y = c_1 e^{3t} + 2c_2 e^{2t} \end{cases}$	2
	ii.	<p>Solve the system:</p> $\begin{cases} \frac{dx}{dt} = 4x - 2y \\ \frac{dy}{dt} = 5x + 2y \end{cases}$	
		<p>Solution: Auxiliary equation is $m^2 - (4 + 2)m + 8 + 10 = 0$ Roots are $m = 3 \pm 3i$ Taking $\begin{cases} x(t) = Ae^{mt} \\ y(t) = Be^{mt} \end{cases}$ & $m = 3 + 3i \therefore x'(t) = 4x(t) - 2y(t)$ $\therefore mAe^{mt} = 4Ae^{mt} - 2Be^{mt}$ $\therefore (4 - m)A - 2B = 0$ as $e^{mt} \neq 0$ \therefore using $m = 3 + 3i$ we get $(1 - 3i)A - 2B = 0$ Take $A = 1 + 3i$ then $(1 - 3i)(1 + 3i) = 2B \therefore B = 5$ $\therefore \begin{cases} x(t) = (1 + 3i)e^{(3+3i)t} \\ y(t) = 5e^{(3+3i)t} \end{cases}$ $\therefore \begin{cases} x(t) = e^{3t}[\cos 3t - 3\sin 3t + i(3\cos 3t + \sin 3t)] \\ y(t) = e^{3t}[5\cos 3t + i(5\sin 3t)] \end{cases}$ Consider, $\begin{cases} x_1(t) = e^{3t}[\cos 3t - 3\sin 3t] \\ y_1(t) = e^{3t}[5\cos 3t] \end{cases}$ and $\begin{cases} x_2(t) = e^{3t}[3\cos 3t + \sin 3t] \\ y_2(t) = e^{3t}[5\sin 3t] \end{cases}$ Then check these solve $\begin{cases} \frac{dx}{dt} = 4x - 2y \\ \frac{dy}{dt} = 5x + 2y \end{cases}$ Also Wronskian of these solutions $W(t) = \begin{vmatrix} e^{3t}(\cos 3t - \sin 3t) & 5e^{3t}\cos 3t \\ e^{3t}(3\cos 3t + \sin 3t) & 5e^{3t}\sin 3t \end{vmatrix} = -15e^{6t} \neq 0$ Hence these are linearly independent solutions $\therefore \begin{cases} x(t) = c_1 e^{3t}[\cos 3t - 3\sin 3t] + c_2 e^{3t}[3\cos 3t + \sin 3t] \\ y(t) = c_1 [5e^{3t}\cos 3t] + c_2 [5e^{3t}\sin 3t] \end{cases}$ is the general solution. </p>	2 1 1 1
	iii.	Solve the following linear system:	

13

			$\begin{cases} \frac{dx}{dt} = 4x + 2y \\ \frac{dy}{dt} = 2x + 4y \end{cases}$	
			Solution: We know that the auxiliary equation of the system $\begin{cases} \frac{dx}{dt} = a_1x + b_1y \\ \frac{dy}{dt} = a_2x + b_2y \end{cases}$ is given by $m^2 - (a_1 + b_2)m + (a_1b_2 - a_2b_1) = 0$. Therefore, the auxiliary equation of the given system is $m^2 - (4 + 4)m + (16 - 4) = 0$. That is $m^2 - 8m + 12 = 0$. Thus, the roots of the auxiliary equation are 2 and 6. Consider the equations: $\begin{cases} 2A + 2B = 0 \\ 2A + 2B = 0 \end{cases}$ by considering $m = 2$. A nontrivial solution of this system is $A = 1$ and $B = -1$. Thus, we have $\begin{cases} x = e^{2t} \\ y = -e^{2t} \end{cases}$ as a solution. Similarly, by considering $m = 6$, we get $\begin{cases} -2A + 2B = 0 \\ 2A - 2B = 0 \end{cases}$. This gives $A = 1$ and $B = 1$ as a nontrivial solution. Therefore, we have $\begin{cases} x = e^{6t} \\ y = e^{6t} \end{cases}$ as another solution. Check that these solutions are linearly independent. Therefore, $\begin{cases} x = c_1e^{2t} + c_2e^{6t} \\ y = -c_1e^{2t} + c_2e^{6t} \end{cases}$ is the general solution of the system.	2 1 1 2
		iv.	Obtain the general solution of a system of homogeneous linear first order O.D.E. with constant coefficients in two variables, when its auxiliary equation has two real and distinct roots	
			Solution: Let m_1 and m_2 be distinct roots of auxiliary equation $m^2 - (a_1 + b_2)m + a_1b_2 - a_2b_1 = 0$ for $\begin{cases} x'(t) = a_1x(t) + b_1y(t) \\ y'(t) = a_2x(t) + b_2y(t) \end{cases} \quad \text{----- (*)}$ Taking, $\begin{cases} x(t) = Ae^{mt} \\ y(t) = Be^{mt} \end{cases}$ We get, $mAe^{mt} = a_1Ae^{mt} + b_1Be^{mt}$ & $mBe^{mt} = a_2Ae^{mt} + b_2Be^{mt}$ $\therefore (m - a_1)A - b_1B = 0$ & $a_2A + (b_2 - m)B = 0$ These are solvable with non-zero values to A & B provided	2 1

14

		$\begin{bmatrix} m - a_1 & -b_1 \\ a_2 & (b_2 - m) \end{bmatrix}$ is singular i.e. provided $\begin{vmatrix} m - a_1 & -b_1 \\ a_2 & (b_2 - m) \end{vmatrix} = 0 \text{ i.e. } m^2 - (a_1 + b_2)m + a_1b_2 - a_2b_1 = 0$ <p>Essentially now only one equation is sufficient as the other equation is a multiple of the first.</p> $\therefore (m - a_1)A - b_1B = 0 \text{ gives } \frac{B}{A} = \frac{m - a_1}{b_1} \text{ whenever } b_1 \neq 0$ <p>Take $A = b_1$ and $B = m - a_1$</p> <p>Then</p> $\begin{cases} x(t) = b_1 e^{mt} \\ y(t) = (m - a_1)e^{mt} \end{cases} \text{ solves } *$ <p>Taking $m = m_1$ and $m = m_2$ we get two solutions with Wronskian $W(t)$</p> $W(t) = \begin{vmatrix} b_1 e^{m_1 t} & (m_1 - a_1)e^{m_1 t} \\ b_1 e^{m_2 t} & (m_2 - a_1)e^{m_2 t} \end{vmatrix} = b_1(m_2 - m_1)e^{(m_1 + m_2)t} \neq 0$ <p style="text-align: right;">as $b_1 \neq 0$ & $m_1 \neq m_2$</p> <p>Gives two linearly independent solutions and a linear combination of these with arbitrary constants c_1 & c_2 gives the general solution</p> $\begin{cases} x(t) = c_1 b_1 e^{m_1 t} + c_2 b_1 e^{m_2 t} \\ y(t) = c_1 (m_1 - a_1)e^{m_1 t} + c_2 (m_2 - a_1)e^{m_2 t} \end{cases}$ <p>Also $(a_2)A + (b_2 - m)B = 0$ gives $\frac{A}{B} = \frac{m - b_2}{a_2}$ whenever $a_2 \neq 0$</p> <p>Take $A = m - b_2$ and $B = a_2$</p> $\begin{cases} x(t) = (m - b_2)e^{mt} \\ y(t) = a_2 e^{mt} \end{cases} \text{ solves } *$ <p>Gives similarly a general solution if $a_2 \neq 0$</p> <p>But if $b_1 = 0$ & $a_2 = 0$ then $m^2 - (a_1 + b_2)m + a_1b_2 - a_2b_1 = 0$ gives</p> $m_1 = a_1 \text{ \& } m_2 = b_2$ $\begin{cases} x(t) = c_1 e^{a_1 t} \\ y(t) = c_2 e^{b_2 t} \end{cases} \text{ is the general solution to } *$	1
			1
			1
Q.5	Attempt any FOUR questions from the following:		(20)
a)	Verify that the following differential equation is exact and solve: $\left(y \left(1 + \frac{1}{x}\right) + \cos y\right) dx + (x + \log x - x \sin y) dy = 0.$		
	Here, $\frac{\partial M}{\partial y} = 1 + \frac{1}{x} - \sin y = \frac{\partial N}{\partial x} \therefore$ exact		2
	Solution is, $c = \int M dx + \int N(\text{terms free from } x) dy$ $= \int \left(y \left(1 + \frac{1}{x}\right) + \cos y\right) dx = y(x + \log x) + x \cos y.$		3
b)	Solve: $\sin^2 y dx + \cos^2 x dy = 0.$		
	Separating the variables, we get,		2
			3

		$\frac{dx}{\cos^2 x} + \frac{dy}{\sin^2 y} = 0$ $\sec^2 x dx + \csc^2 y dy = 0.$ <p>Integrating we get, $\tan x - \cot y = c.$</p>	
	c)	Solve the differential equation $y'' + y = x$ by the method of variation of parameters.	
	Ans	<p>Associated auxiliary equation of homogeneous system is $x^2 + 1 = 0$ hence $y_1(x) = \cos x$ and $y_2(x) = \sin x$ are the linearly independent solutions of homogeneous system. $y_p(x) = v_1(x)y_1(x) + v_2(x)y_2(x)$</p> <p>Is particular solution of non-homogeneous system. Now $W(y_1, y_2) = 1$</p> $v_1(x) = \int -x \sin x dx = x \cos x - \sin x$ $v_2(x) = \int x \cos x dx = x \sin x + \cos x \therefore \text{General solution is } y(x),$ $y(x) = \cos x + c_2 \sin x + (x \cos x - \sin x) \cos x + (x \sin x + \cos x) \sin x$	2 1 1 1 1
	d)	Show that $y = c_1 x + c_2 x^{-2}$ is a solution of $x^2 y'' + 2xy' - 2y = 0$ on any interval not containing the origin	
	Ans	$x^2 y'' + 2xy' - 2y = 0 \therefore y'' + \frac{2x}{x^2} y' - \frac{2}{x^2} y = 0$ $\therefore P + Qx = 0, \text{ Where } P = \frac{2x}{x^2}, Q = \frac{-2}{x^2} \therefore y_1 = x \text{ is a solution} \therefore y_1' = 1$ <p>And $y_1'' = 0$</p> <p>Clearly, $x^2 y_1'' + 2xy_1' - 2y_1 = 0$ therefore y_1 is a solution to given differential equation.</p> <p>Similarly, for,</p> $y_2 = x^{-2}$ $\therefore y_2' = -2x^{-3}$ <p>And $y_2'' = 6x^{-4}$</p> <p>Clearly, $x^2 y_2'' + 2xy_2' - 2y_2 = 0$ therefore y_2 is a solution to given differential equation.</p> <p>Here y_1 and y_2 are linearly independent, also $x \neq 0$</p> $\therefore y = c_1 x^{-1} + c_2 x^5 \text{ is a solution of } x^2 y'' - 3xy' - 5y = 0 \text{ on any interval, not containing the origin.}$	1 1 1 1 1 1
	e)	Show that both $x_1 = 2e^{5t}, y_1 = e^{5t}$ and $x_2 = e^{-t}, y_2 = -e^{-t}$ are solutions of the system $\begin{cases} \frac{dx}{dt} = 3x + 4y \\ \frac{dy}{dt} = 2x + y \end{cases}$	
		Also show that these two solutions are linearly independent	
		<p>Solution:</p> <p>Consider. $\begin{cases} x = 2e^{5t} \\ y = e^{5t} \end{cases}$</p> <p>Therefore,</p> $\frac{dx}{dt} = 10e^{5t} \quad \frac{dy}{dt} = 5e^{5t}$ <p>and $3x + 4y = 6e^{5t} + 4e^{5t} = \frac{dx}{dt} = 10e^{5t}$</p>	2

	$2x + y = 4e^{5t} + e^{5t} = \frac{dy}{dt} = 5e^{5t}$ <p>Thus, $\begin{cases} x = 2e^{5t} \\ y = e^{5t} \end{cases}$ satisfies the given system.</p> <p>Similarly, $\begin{cases} x = e^{-t} \\ y = -e^{-t} \end{cases}$ consider. Therefore,</p> $\frac{dx}{dt} = -e^{-t} \text{ and } \frac{dy}{dt} = e^{-t}$ $3x + 4y = 3e^{-t} + 4(-e^{-t}) = \frac{dx}{dt} = -e^{-t}$ $2x + y = 2e^{-t} + (-e^{-t}) = \frac{dy}{dt} = e^{-t}$ <p>Thus, $\begin{cases} x = e^{-t} \\ y = -e^{-t} \end{cases}$ too satisfies the given system.</p> <p>Consider the Wronskian of the two solutions:</p> $W = \begin{vmatrix} 2e^{5t} & e^{-t} \\ e^{5t} & -e^{-t} \end{vmatrix} = -3e^{4t}$ <p>Since, exponential function never vanishes, $W \neq 0$. Thus, these solutions are linearly independent</p>	2
f)	<p>Show that $(-2e^t \sin 2t, e^t \cos 2t)$ and $(2e^t \cos 2t, e^t \sin 2t)$ are linearly independent solutions of</p> $\begin{cases} \frac{dx}{dt} = x - 4y \\ \frac{dy}{dt} = x + y \end{cases}$	1
	<p>Solution:</p> <p>Consider $\begin{cases} x = -2e^t \sin 2t \\ y = e^t \cos 2t \end{cases}$. Therefore,</p> $\frac{dx}{dt} = -2(2e^t \cos 2t + e^t \sin 2t) \quad \frac{dy}{dt} = -2e^t \sin 2t + e^t \cos 2t$ $= -2e^t \sin 2t - 4e^t \cos 2t \quad \text{and} \quad = x + y$ $= x - 4y$ <p>Thus, $\begin{cases} x = -2e^t \sin 2t \\ y = e^t \cos 2t \end{cases}$ satisfies the given system.</p> <p>Similarly, consider $\begin{cases} x = 2e^t \cos 2t \\ y = e^t \sin 2t \end{cases}$</p> $\frac{dx}{dt} = 2(-2e^t \sin 2t + e^t \cos 2t) \quad \frac{dy}{dt} = 2e^t \cos 2t + e^t \sin 2t$ $= 2e^t \cos 2t - 4e^t \sin 2t \quad \text{and} \quad = x + y$ $= x - 4y$	2
		1

17

	<p>Thus, $\begin{cases} x = 2e^t \cos 2t \\ y = e^t \sin 2t \end{cases}$ satisfies the given system.</p> <p>Now consider the Wronskian of the two solutions:</p> $W = \begin{vmatrix} -2e^t \sin 2t & 2e^t \cos 2t \\ e^t \cos 2t & e^t \sin 2t \end{vmatrix}$ $= -2e^{2t} \sin^2 2t - 2e^{2t} \cos^2 2t$ $= -2e^{2t} (\sin^2 2t + \cos^2 2t)$ $= -2e^{2t}$ <p>Since, exponential function never vanishes, we have $W \neq 0$. Thus, the solutions are linearly independent.</p>	<p>1</p> <p>1</p>
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