Solution

1T00426 - T.E.(Biotechnology Engineering)(SEM-VI)(Choice Base) / 88845 - Process Control & Instrumentation.

Q2 a. Given $y(t) = te^{-t}$

Take Laplace on both the sides

$$Y(s) = \frac{1}{\left(s+1\right)^2} X(s)$$

Hence we have find the transfer function now they have stated X(s)is given stepinput

$$Y(s) = \frac{1}{(s+1)^2} \frac{1}{s}$$
$$Y(s) = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{(s+1)^2}$$
$$A = 1, B = -1, C = -1$$

Taking laplace inverse we have

$$Y(t) = \left(1 - e^{-t} - te^{-t}\right)$$

Q2b.

The step response equation is $Y(t) = A \left(1 - e^{-\frac{t}{\tau}} \right)$

$$Y(t) = y-y_s \tau = 6 \text{ sec}, A = (100-80) = 20$$

i)
$$y - 80 = 20 \left(1 - e^{-\frac{6}{6}} \right)$$

 $y = 80 + 12.64 = 92.64 \,^{\circ}\text{C}$
ii) $y - 80 = 20 \left(1 - e^{-\frac{t}{6}} \right)$
 $90 - 80 = 20 \left(1 - e^{-\frac{t}{6}} \right)$
 $t = 4.15 \, \text{sec}$

iii) 90% of ultimate response is $0.9 \times 100 = 90$ °C Hence answer is same as above i.e. t = 4.15 sec

Q2c



At steady state:

$$q_s - \frac{h_s}{R_1} - \frac{h_s}{R_2} = A \frac{dh_s}{dt} \quad -----(2)$$

Deviation variable form by subtracting equation(2) from equation (1)

Now eqn (3) becomes:

Taking laplace transform of equation(4):

$$Q(s) - \frac{H(s)}{R_1} - \frac{H(s)}{R_2} = A sH(s) - H(0)$$

 $H(0) = 0$

$$Q(s) - \frac{H(s)}{R_1} - \frac{H(s)}{R_2} = A sH(s)$$
$$Q(s) - H(s) \left(\frac{1}{R_1} + \frac{1}{R_2}\right) = A sH(s)$$

Q(s) = A sH(s) + H(s) $\left(\frac{1}{R_1} + \frac{1}{R_2}\right)$
$Q(s) = H(s) \frac{(AR_1R_2 s + R_1 + R_2)}{R_1R_2}$
$H(s) = R_1 R_2$
$\overline{\mathbf{Q}(\mathbf{s})} = \overline{\left(\mathbf{AR}_{1}\mathbf{R}_{2}\mathbf{s} + \mathbf{R}_{1} + \mathbf{R}_{2}\right)}$
$H(s) = 2 \times 5$
$\overline{\mathbf{Q}(\mathbf{s})} = \overline{\left(10\mathrm{A}\mathrm{s}+7\right)}$
H(s) 10/7
$\overline{\mathbf{Q}(\mathbf{s})} = \overline{\left(\left(\frac{10}{7}\right)2\mathbf{s}+1\right)}$
H(s) 1.43
$\overline{\mathbf{Q}(\mathbf{s})} = \overline{\left(2.85\mathbf{s}+1\right)}$

Q3a i. The characteristic equation is:

$$s^4 + 4s^3 + 6s^2 + 4s + (1 + K) = 0$$

Arranging in Routh Array:

$$s^{4} 1 \quad 6(1+k)$$

$$s^{3} 4 \quad 4$$

$$s^{2} 5 \quad 1+k$$

$$s \quad 4 - \frac{4}{5}(1+k)$$

$$1 \quad 1+k$$

For the system to be unstable:

$$4\left(1 - \left(\frac{1+k}{5}\right)\right) < 0$$
$$1 < \frac{1+k}{5}$$

k > 41 + k < 0k < -1k > -1

The system is stable at: $-1 \le k \le 4$

(ii) For two imaginary roots:

$$4 = \frac{4}{5}(1+k); k = 4$$

Values of complex roots are:

$$5s^2 + 5 = 0$$
$$s = \pm i$$

(iii)

To find other two roots:

$$(s - s_1)(s - s_2)(s - s_3)(s - s_4) = s^4 + 4s^3 + 6s^2 + 4s + (1 + k)$$

Where $s_1 = +i$ and $s_2 = -i$
Solving and comparing the coefficients of both the sides for s_3 and s_4 :
 $s_3, s_4 = -2 \pm i$

Q4a. Root locus for the open loop transfer function:

 $G(s)H(s) = \frac{\mathrm{K}}{\mathrm{s}(\mathrm{s}^2 + 4\mathrm{s} + 8)}$

Solution: (i) No. of open-loop poles n = 3No. of open-loop zeros m = 0(ii) No. of separate root loci n - m = 3(iii) Open-loop plots are at s = 0, s = -2 + 2j, s = -2 - 2j(iv) Asymptotic angles are $\theta_A = \frac{(2q+1) \, 180^\circ}{n-m}, \ q = 0, \ 1, \ 2$ $q = 0, \quad \theta_1 = \frac{180}{3} = 60^\circ$ $q = 1, \quad \theta_2 = \frac{180 \times 3}{3} = 180^\circ$ $q = 2, \quad \theta_3 = \frac{180 \times 5}{3} = 300^{\circ}$ $\sigma_c = \frac{\sum P - \sum Z}{n - m} = \frac{-2 + 2j - 2 - 2j}{3} = -1.33$ (v) Centroid (vi) Breakaway point: 1 + G(s) H(s) = 0; $1 + \frac{K}{s(s^2 + 4s + 8)} = 0$ $K = -(s^2 + 4s^2 + 8s)$ $\frac{dK}{ds} = -(3s^2 + 8s + 8) = 0$ $s = \frac{-8 \pm \sqrt{64} - 96}{2}$ $=\frac{-8\pm 5.66\,j}{2}=-4\pm 2.83\,j$ (vii) Point of intersection with imaginary axis. $1 + \frac{K}{s(s^2 + 4s + 8)} = 0 \implies s^3 + 4s^2 + 8s + K = 0$ Routh array is For sustained oscillation, $\frac{32 - K}{4} = 0 \implies K = 32$ Auxiliary eqn. is $4s^2 + K = 0$; $4s^2 = 32$; $s^2 = -8$; $s = \pm j 2.83$ (viii) Angle of departure at s = -2 + j 2 is $\theta_d = 180^\circ - (90^\circ + 135^\circ) = -45^\circ$



Q5a The Bode plot for $G(s)H(s) = \frac{100}{s(s+0.5)(s+10)}$

Step1: $G(s)H(s) = \frac{100}{s0.5(2s+1)10(0.1s+1)} = \frac{20}{s(2s+1)(0.1s+1)}$

Step2: K=20

1 pole at origin $\frac{1}{s}$

Simple pole $\frac{1}{(2s+1)}$, $\tau_1 = 2$, wc₁ = 1/ $\tau_1 = 0.5$

Simple pole
$$\frac{1}{(0.1s+1)}$$
, $\tau_1 = 0.1$, wc₁ = 1/ $\tau_1 = 10$

Step3:Magnitude plot analysis

- i) For K=20, 20 log K= 26.02dB
- ii) For 1 pole at origin, straight line with slope -20 dB/decade will pass through w=1 and 20log K=26.02 dB line
- iii) Overall magnitude plot will continue with slope -20 dB/decade till wc₁=0.5. Now from wc₁=0.5 onwards as simple pole is occurring, slope is going to change by -20 dB/decade hence resultant will have slope -40 dB/decade representing addition of K, 1/s and 1/(1+2s). This will continue wc₂ = 10
- iv) At wc2 = 10 again simple pole is occurring and hence slope will further change by -20 dB/decade. So resultant will have slope of -60 dB/decade and continue as no further terms exist.

Step 4

Phase Angle plot :

$$G(j\omega) H(j\omega) = \frac{20}{j\omega(1+2j\omega)\left(1+j\frac{\omega}{10}\right)}$$

$$\geq G(j\omega) H(j\omega) = \frac{20+j0}{2j\omega(1+2j\omega)\left(1+j\frac{\omega}{10}\right)}$$

$$\geq 20 + j0 = 0^{\circ}$$

$$\geq \frac{1}{j\omega} = -90^{\circ}, \quad 1 \text{ pole at origin}$$

$$\leq \frac{\cdot 1}{1+2j\omega} = -\tan^{-1} 2\omega \qquad \leq \frac{1}{1+j\frac{\omega}{10}} = -\tan^{-1}\frac{\omega}{10}$$

∴Phase A	ngle Table	à.
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ω	1 jω	- tān ⁻¹ 200	$-\tan^{-1}\frac{\omega}{10}$	φ _R
0.1	- 90°	- 11.3°	- 0.57°	- 101.87°
0.5	- 90°	- 45°	- 2.86°	- 137.86°
1	- 90°	- 63.43°	- 5.71°	- 159.14°
2	ı – 90°	- 75.96°	- 11.3°	- 177.26°
.10	- 90°	- 87.13°	- 45°	- 222.13°
50	- 90°	- 89.42°	- 78.69°	- 258.11°
00	- 90°	- 90°	- 90°	- 270°

Bode Plot:



0°