[ Marks: 80]

4. Assume suitable data is necessary. 1. Attempt following. 20 a) Define embedded systems. Explain types of embedded systems and give example. b) Explain function of following registers. a) BSR b) FST c) W d) PC c) Explain following PIC 18 instructions. a) BTFSC b) TBLRD\* d) Draw and explain interfacing of serial EEPROM with PIC 18 in SPI mode. 2. Explain working of timer 1 of PIC 18 with prescaling feature in detail. **20** Write PIC 18 program to receive byte of data serially and put term on PORTB. Set the 20 baud rate at 9600. 3. a) Explain external interrupts of PIC 18 in detail. 10 b) Explain ADC module of PIC 18 in detail. **10** 4. a) Explain interfacing of DAC to PIC 18 and write a program to generate sawtooth 10 waveform. b) Interface a seven segment LED to PIC 18 and write a program to display decimal **10** counter (0 to 9) on it. 5. a) Interface D.C. motor to PIC 18. Write a program to rotate motor with 50% duty cycle 10 using PWM mode of CCP module. b) What is priority inversion? Explain with suitable example. **10** 6. Write short notes on any 4 20 a) POPTB change interrupt b) Interrupt latency c) I<sup>2</sup> C module of PIC 18 d) Design challenges for embedded system e) Memory organization of PIC 18

[Time: 3 Hours]

2. Attempt any 3 questions out of remaining questions.

1. Question No. 1 is compulsory.

3. All questions carry equal marks.

N.B:

Please check whether you have got the right question paper.